

## **FLOMOTION LT330**

Ultrasonic Level Transmitter USER'S MANUAL

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## **Chapter 1. Introduction**

#### **About the FLOMOTION LT330**

The FLOMOTION LT330 operates on the principle of timing the echo received from a measured pulse of sound transmitted in air and utilizes "state of the art" echo extraction technology.

Easy calibration and maintenance free performance mean that you can install the LT330 Series rapidly and with confidence.

The LT330 Series can show level, space, distance, on the display. The switched outputs can be programmed to give an 'ON' and 'OFF' point for external control. There is a 4-20 mA output that can be connected to a remote chart recorder or PLC, to monitor level, space or distance, dependant on the measurement mode selected, and provides a 'fault condition' alarm of either 3.8mA or 21mA.

The LT330 Series has an IP67 lid covering an integral LCD display and 5 buttons used for programming purposes, together with 4 LED's which provide status information whilst in RUN and PROGRAM Mode.



## **Product Specification**

## Physical

Dimensions	Overall: 4.61 D x 8.22 in. H (117 D x 209 H mm)
Process Connection	Mounting: 2" NPT
Weight	Nominal: 3.3 lb (1.5 kg)
Case material/description	Polypropylene
Environmental	Nema 6 (IP67)
Temperature	-4°F to 185°F (-20°C to +85°C)
Pressure	up to 29 psi (2 Bar)
Accuracy	0.2% of the measured range
Resolution	0.039% of full scale (1mm)
Max. Range	Liquids 20 ft (6m) or 33 ft (10m)
Beam Angle	8° at -3dB
Damping Rate	Adjustable from 0.1m/min to 100m/min
Temperature Compensation	Fully compensated via integral temperature sensor over entire
	operational span
Analog output	4-20mA into max 750Ω (user adjustable)
	Fault condition
	Alarm 3.8mA or 21mA (user selectable)
Display	5 Digit LCD Display
On-board programming	5 tactile push button keys
Power supply	DC18-30V (std)
Current Consumption	Less than 21mADC
CE approval	EMC approval to BS EN 61326-1:2006 (Class A),.

## **Chapter 2. Installation**

The FLOMOTION LT330 is composed of one controller unit and one sensor

### **Power Supply Requirements**

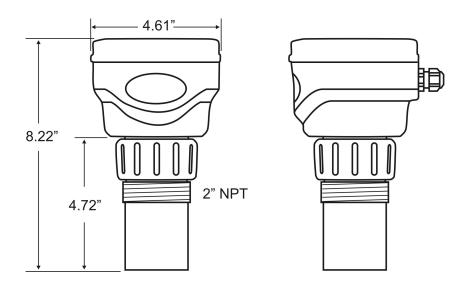
The LT330 operates from a DC supply of 18–30V and will typically draw less than 21mADC. All electronic products are susceptible to electrostatic shock, so follow proper grounding procedures during installation.

The compact one-piece construction of the LT330 can be mounted easily using the integral nose thread (2"NPT).

When choosing a location to mount the LT330, bear in mind the following:

- For easy access to the LCD display and programming buttons mount it where it is easily accessible.
- The ultrasonic signal path should be free of falling material and obstructions such as pipes, beams etc.
- The LT330 should be mounted at least 1.0ft (30cm) above the maximum level of the material and be perpendicular to the surface.
- The mounting surface should be vibration-free.
- The ambient temperature is between -4° to 185°F (-20° to 85°C)
- There should be no high voltage cables or electrical inverters close by.
- Do not use any metal substances when installing.

#### **Dimensions**

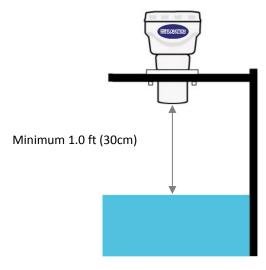


## **Outdoor and Open Vessel Installation**

The LT330 can be simply mounted on a bracket, suitable for the application and secured using the thread located at the top of the transducer (2" NPT).

Care should be taken to ensure that the LT330 is not installed in direct sunlight, in order to avoid errors in the measurement of ambient temperature.

Attention should also be taken, when mounting the unit, to ensure that strong windy conditions are avoided, wherever possible, to prevent abnormal operation.



#### **Closed Vessel Installation**

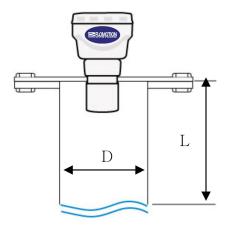
The LT330 can be simply screwed into a flange and secured using the thread located at the top of the transducer (2"NPT).

Where possible use a flange made of a synthetic material such as PVC, to avoid vibration.

Place a rubber gasket between the flange of the LT330 and the connection to the vessel to avoid vibration.

## **Stand Pipe Installations**

When mounting the LT330 to a standpipe care should be taken to ensure that the standpipe is of sufficient space with reference to its length, see the table below for details:



D	Length
3.15 in. (80mm)	9.22 in. (234mm)
3.94 in. (100mm)	11.42 in. (290mm)
5.91 in. (150mm)	16.93 in. (430mm)
7.87 in. (200mm)	22.44 in. (570mm)

When using a standpipe, fixed to the top of a vessel, ensure that the open end of the standpipe is clear of any obstructions such as weld seams, gaskets etc. in order to avoid unwanted signal returns. If using standpipes, which extend into the vessel, beyond the blanking distance, but not as far as the empty level, then the open end of the standpipe should be cut to an angle of 45°.



The maximum level (100% of Span) is inside the Blanking Distance



Pipe should be free of obstructions such as weld seams



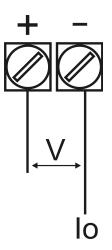
Incorrect Standpipe size

## **Cable Entry**

Even though the LT330 has a high NEMA rating, it can't be protect against moisture which comes in continuously for a long time. The LT330 Series has a single PG13.5 cable entry, fitted with a suitable seal, to ensure moisture protection is maintained. After connecting the cable, route the cable down from the controller.

## **Terminal Connection Details**

The LT330 Series terminal connections are detailed below.



- V+ : Direct current(DC) input terminal (max.30V DC)
- lo : Current Output terminal (4-20mA)

## Important Information

If the equipment is installed or used in a manner not specified in this manual, then the protection provided by the equipment may be impaired.

## **Preparation for Operation**

Before switching on, check the following:

- The LT330 is mounted correctly.
- The power supply is correctly installed.

## Maintenance

There are no user-serviceable parts inside LT330, if you experience any problems with the unit, then please contact your local distributor for advice. To clean the equipment, wipe with a damp cloth. Do not use any solvents on the enclosure.

# **Chapter 3. How To Use LT330 Series**

### Display

While in the Run Mode, the 5-digit LCD display will show the current level reading in feet or meters, it will also display a flashing "0" when a fault condition (Loss Of Echo) is detected. When in the Program Mode the display is used to read information on the Menu Options and the values entered.

There are two operating modes for your LT330, Run Mode and Program Mode.



## **Measuring Mode**

This mode is used once the LT330 has been set up in program mode. It is also the default mode that the unit reverts to when it resumes operation after a power failure.

When the LT330 is switched on for the first time, it will display, in centimeters, the distance from the transducer face to the target.

After programming is complete, any switched outputs that are set will operate when the level reaches the relevant setpoints. While in Run Mode the Detect and Distance LED's provide information on the status of the signal.

## **Program Mode**



This mode is used to set up the LT330 or change information already set, this is achieved by using the 5 push buttons located either side of the display.

Entering a value for each of the menu options that are relevant to your application provides all the programming information.

The menu number is displayed with alphabet "P". Up and Down Key makes move to another menu.

#### How to use the buttons

To access the Program Mode simply press the "Menu" button. Confirmation that you have entered the Program Mode will be given by the Detect and Mode (Level, Distance or Space) LED's being extinguished, and the Software Version will also appear in the display. Each subsequent press of the UP or DOWN buttons will advance you through the options,

• Access the Program Mode:	MENU
Move to other group option:	<b>A V</b>
Move inside of each group or	otion: MENU
Change option value:	•
Return to Measuring Mode:	RUN
Return to Program Mode:	ESC

## **Examples**

[Example] Changing the bottom distance value from 10 meters to 9 meters,



Press "MENU" button for 1 second in measuring mode.



2. Software version displays for 2 seconds.



3. After showing the S/W version, the menu number displays.



4. Use "UP" and "DOWN" button go to P04.



5. Press "menu" button, the first digit flickers. Using the "UP" and "DOWN" buttons change to the desired value.



6. After the first digit is set, press "MENU "button to move the second digit



7. After all values are set, press "RUN" to save the value. This also returns you to measuring mode.



8. If "ESC" button is pressed instead of "RUN" button, it returns you to the menu which you selected right before. The setting value isn't saved until the "Run" mode is selected.

#### **LED Functions**

There are 4 LED's, located above the display their functions are as follows:

LED	Condition	Function
Detect & Level	Flashing together	Indicates Normal Operation Mode selected = Level
Detect & Distance	Flashing together	Indicates Normal Operation Mode selected = Distance
Detect & Space	Flashing together	Indicates Normal Operation Mode selected = Space
Detect	Flashing alone	Indicates that LT330 is detecting an echo but checking if the value is correct.
None	All Of Display indicates flashing "E*"	Indicates that LT330 has gone into Fail condition. E0 means there is no reflected echo received. E1 means transducer and electronic part is disconnected

### What to Do First

When you first power the LT330 on, it will be reading the distance from the face of the transducer to the surface in meters or feet, as shown on the display.



TIP

In some applications it is simplest to empty the vessel, take a reading from the LT330 for distance and then setup the empty level to this figure.

Once you are satisfied with the installation, and the LT330 is reading what you would expect in terms of distance from the face of the transducer to the material level, then you can set up the options as detailed in Chapter 4 Program.

## Chapter 4. Program

This chapter describes all of the menu options in the LT330, in numerical order. Press the menu button to change a menu option. Select from menu 1 to menu 18 by moving up or down with the arrow keys. The grey marked cell below is the factory set value.

## **Application Menu**

#### [P01] Operating Mode

This option sets the mode of operation when in measuring mode, and can be set to one of the following:

Option	Description
1 = Level	Display shows how full the vessel is with respect to the Empty (0 % of Span)
2 = Distance	Display shows the distance from the transducer face to the surface.
3 = Space	Display shows how an empty vessel is with respect to Full (100 % of Span) i.e. how much space is available in the vessel.

#### [P02] Display

This option is to choose the measuring unit between meter and feet.

Option	Description
1	Meter
2	FT

### [P03] Display

This option sets the display unit of LCD display among 1. Feet (m), 2. mA, or 3. %

Option	Description
1	Distance by selected measuring unit
2	mA (Current value)
3	% (Percentage)

### [P04] Empty Level

This option is to set the maximum distance from the face of the transducer to the bottom distance, in feet (ft). The tank has to be empty. User can set factory set value with up and down keys. Maximum values are shown below.

Option	Description
LT3301	20ft
LT3302	33ft

This option is the distance from the face of the transducer that is not capable of being measured, and is pre-set to 1 foot (30cm). It should not be set to less than this figure, but can be increased if required.

## **Current Output Menu**

#### [P06] 4 mA Setpoint

The range of current is from 4mA to 20mA. This option sets the distance (or level or space, depending on the selected Operating Mode (Option 01) at which the 4mA output will occur. By default 4mA will represent Empty (0% of Span)

#### [P07] 20 mA Setpoint

The range of current is from 4mA to 20mA. This option sets the distance (or level or space), depending on the selected Operating Mode (Option 01) at which the 20mA output will occur. By default 20mA will represent Full (100% of Span). If you set the lowest point as 20mA, 4mA should be set for highest point.

#### Important Information

The Span is the maximum working distance from Empty (0%) to Full (100%), and is automatically calculated as Empty Level (Option 04) minus Blanking Distance (Option 05). Except for when Operating Mode (Option 01) = Distance in this case the Span is the same as the Empty Level (Option 04)

#### [P08] mA Fail-safe Value

If the LT330 Series fails to receive a valid echo return from the target, then the mA output can be used to indicate a fault condition (Loss of Echo). This option determines the mA output value which will indicates such a condition.

Option	Description	
1 = 3.8mA	Fault condition (LOE) indicated by 3.8mA	
2 = Hold	The previous measured value outputs	
3 = 22mA	Fault condition (LOE) indicated by 22mA	

### [P09] mA Fail-safe Time

In the event of a fail-safe condition occurring (LOE - Loss of Echo) the fail safe timer determines the time before the mA output indicates a fault condition (LOE). If a fault condition is present for the duration of the fail-safe time, it regards it as an error. The time range is between 20 and 900 seconds. The pre-set is 300 seconds.

## **Compensation Menu**

#### [P10] Damping Rate

The measured value is not displayed in real time. The value is generated by averaging over a certain time period. This can be more effective for accurate value. But when the level is changing dramatically, it can cause some inaccuracy. For more accurate level, choose the suitable damping rate in accordance with the velocity of level. The pre-set is 1.0

Option		Description
0.01	0.01m/min	Responds to changes to a max. 0.01m/min (Slowest)
Step: 0.01		Minimum: 0.01 - Maximum: 100.0
100.0	100m/min	Responds to changes to a max. 100m/min (Fastest)

#### [P11] Detection Threshold Voltage

This option determines detectable size of the return echo. This is useful when the first return echo is needed in a condition where small objects create various kinds of return echoes. In that case set the value higher, so the signal is stronger than the noise, but less likely to detect small echoes. The 8 is equal to 0.8V. The pre-set is "3."

No.	3	4	5	6	7	8	9	10	11	12	13	14	15
Voltage			←Lo	)W							High →		

#### [P12] Output Power

This option is used to set the power output from the transducer to suit varying applications. By reducing the power emitted the beam angle will be effectively reduced and can be applied as detailed below:

Option	Description
1 = Low Power	For use on short range applications
2 = Normal Power	For use in normal conditions
3 = High Power	For use in outdoor applications, long range measurement
4 = Maximum Power	For use in difficult applications where conditions are dusty, steamy or turbulent.

#### [P13] Sound Velocity

This option allows for the velocity of sound to be changed according to the atmosphere the transducer is operating in. By default the velocity is set for sound traveling in air at a temperature of 32°F (0°C).

The table below gives details of the velocity of sound in various gaseous atmospheres. In all cases the velocity indicated is that in a 100% gaseous atmosphere at 32°F (0°C). In atmospheres less than 100% it may be necessary to check the level indicated at near empty and near full and compare with the actual level, several times, then adjust the Sound Velocity accordingly to obtain an accurately displayed reading.

Gas	Sound Velocity
Chlorine	206 m/sec
Carbon Dioxide.	259 m/sec
Argon	308 m/sec
Oxygen	316 m/sec
Air	331.5 m/sec
Ammonia	415 m/sec
Methane	430 m/sec
Helium	435 m/sec
Neon	965 m/sec

#### [P14] Vapor Temperature Compensation

The sound velocity in air increases or decreases at a uniform rate of 60cm/°C, however in atmospheres other than air it will change at a different rate.

This option allows the rate of change in cm/°C to be set according to the present atmosphere and temperature. The level indicated, should be compared with the actual level, several times, then Vapor Temperature Compensation adjusted accordingly, to obtain an accurately displayed reading. The pre-set is 60cm/°C.

## [P15] Detection Algorithm

This option determines the detection algorithm. The returned signal can be strong or weak according to field conditions. This option chooses what signal is effective.

Option	Description
1	Automatic
2	Effective only for the First signal

## [P16] Detection Target

The signals reflectance is subject to change by the measuring target.

Option	Description
1	Liquid
2	Bubble Liquid
3	Solid
4	Powder

#### [P17] Outputs Simulation Menu

When the LT330 is operated with other instruments in a current loop, this menu can be used to simulate the output current from the LT330 for testing purposes.

#### [P17] Simulation

Enter the range desired. LT330 sends out the output current for the range. For example, if you put 10 feet, the output current is sent out in response to 10 feet. If the range value is over the lowest level or highest level, the error signal is sent out.

#### **Password Menu**

#### [P18] Password

This option prevents malicious and unskilled user from changing option values. Once this option is set, the password is required whenever entering into program mode. **The initial password is "0"** 



- 1. If the password is not "0", the "pass" shows on the display.
- 2. After 1 second, it moves to setting mode automatically. The first digit flickers. Use "UP" and "DOWN" button to set the password. Use "MENU" button to move the digit position.
- 3. After setting password, press "RUN" button, the password is saved and return to the program mode.
- 4. When the password is incorrect, the error message shows on the display. After 1 second it returns to setting password mode.

IMPORTANT - Write the password down. If forgotten it may not be recoverable.

\*\* If you forget the password, please contact the manufacturer.

# **Chapter 5. Troubleshooting**

This section describes some problem symptoms, with suggestions as to what to do.

Symptom	Cause	What to Do
The level changes faster then reasonable.	Motor or mixer is installed.	Set the velocity lower than current setting value.     OR     The level should be moved to another position where it is not affected by the machinery.
The level changes irregularly	Barrier within the ultrasonic range.	Set the velocity lower than current setting value.     OR     Set the Detection Threshold Voltage lower than current voltage.     OR     Check the sensor bottom surface to see if there is any foreign debris.
The level shows only within blanking distance	Error caused by the protrusions in the nozzle of the reservoir.	1. Check the nozzle inside surface. OR 2. Check the nozzle diameter which is recommended in the manual. OR 3. Increase the blanking distance not over the highest level point.
The level is incorrect in the sealed space.	The pressure is increased by gas generation.	Set the sound velocity according to the medium.     OR     Install ventilation.

## **Menu Option Record Sheet**

## **LT330 Series Application Menu**

	List	Values Note					
Menu N	No. Description	Factory Set	1	2	3	4	5
P01	Operating Mode	1 = Level					
P02	System Unit	1 = FT					<u> </u>
P03	Display	1=Dist, 2=mA, 3=%					-
P04	Empty Level	Empty Dist. / FT					
P05	Blanking Distance	1 FT					-
0	10.45.41						
Current P06	t Output Menu 4mA Setpoint	0					Τ
P07	20mA Setpoint	5.00					<u> </u>
	•						<u> </u>
P08	mA Fail Safe Value	3 = 22mA					<u> </u>
$D \cap O$	Fail Safe Time	300 sec					
P09	raii Sale Tille	300 Sec					
	ensation Menu Damping Rate	1.00					
Compe	ensation Menu Damping Rate DetectionThreshold						
Compe P10	ensation Menu Damping Rate	1.00					
Compe P10 P11	ensation Menu Damping Rate DetectionThreshold Temperature	1.00					
Compe P10 P11	Damping Rate  DetectionThreshold Temperature Output Power	1.00					
Compe P10 P11 P12 P13	ensation Menu Damping Rate DetectionThreshold Temperature Output Power Sound Velocity	1.00 3 2 331.5					
Compe P10 P11 P12 P13	Damping Rate DetectionThreshold Temperature Output Power Sound Velocity Vapor Temp. Comp.	1.00 3 2 331.5 60					
Compe P10 P11 P12 P13 P14 P15	Damping Rate DetectionThreshold Temperature Output Power Sound Velocity Vapor Temp. Comp. Detection Algorithm Detection Target	1.00 3 2 331.5 60					
Compe P10 P11 P12 P13 P14 P15 P16	ensation Menu Damping Rate DetectionThreshold Temperature Output Power Sound Velocity Vapor Temp. Comp. Detection Algorithm Detection Target	1.00 3 2 331.5 60					
Compe P10 P11 P12 P13 P14 P15	Damping Rate DetectionThreshold Temperature Output Power Sound Velocity Vapor Temp. Comp. Detection Algorithm Detection Target	1.00 3 2 331.5 60 1					
Compe P10 P11 P12 P13 P14 P15 P16 Outputs	ensation Menu Damping Rate DetectionThreshold Temperature Output Power Sound Velocity Vapor Temp. Comp. Detection Algorithm Detection Target	1.00 3 2 331.5 60 1					